



Logics with Neural Network Semantics

based on my dissertation (coming soon!)
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Introduction

Assume: All neural networks N have **binary activations**. Nets may be recurrent, but every activated state S must eventually stabilize to a unique fixed point.

Definition. The **closure** $\text{Clos}(S)$ over N gives this unique fixed point—the set of nodes that are activated by S .

Think of this as the “spread” of S throughout the net.

Key Idea: We can interpret logics directly over neural networks using $\text{Clos}(S)$. Let’s first look at two logics:

- A **conditional logic** $L_{\Rightarrow}$ whose conditional $\varphi \Rightarrow \psi$ is interpreted as saying the net *classifies* φ as ψ :

$$N \models \varphi \Rightarrow \psi \quad \text{iff} \quad \text{Clos}(\llbracket \varphi \rrbracket) \supseteq \llbracket \psi \rrbracket$$

- A **non-normal modal logic** L_C whose modality $\langle C \rangle \varphi$ is interpreted as the closure $\text{Clos}(\llbracket \varphi \rrbracket)$ in the neural net:

$$N, n \Vdash \langle C \rangle \varphi \quad \text{iff} \quad n \in \text{Clos}(\llbracket \varphi \rrbracket)$$

I also include two helper operators, $\langle K \rangle \varphi$ and $A\varphi$.

Note 1. $\llbracket \varphi \rrbracket$ is shorthand for $\{m \mid N, m \Vdash \varphi\}$

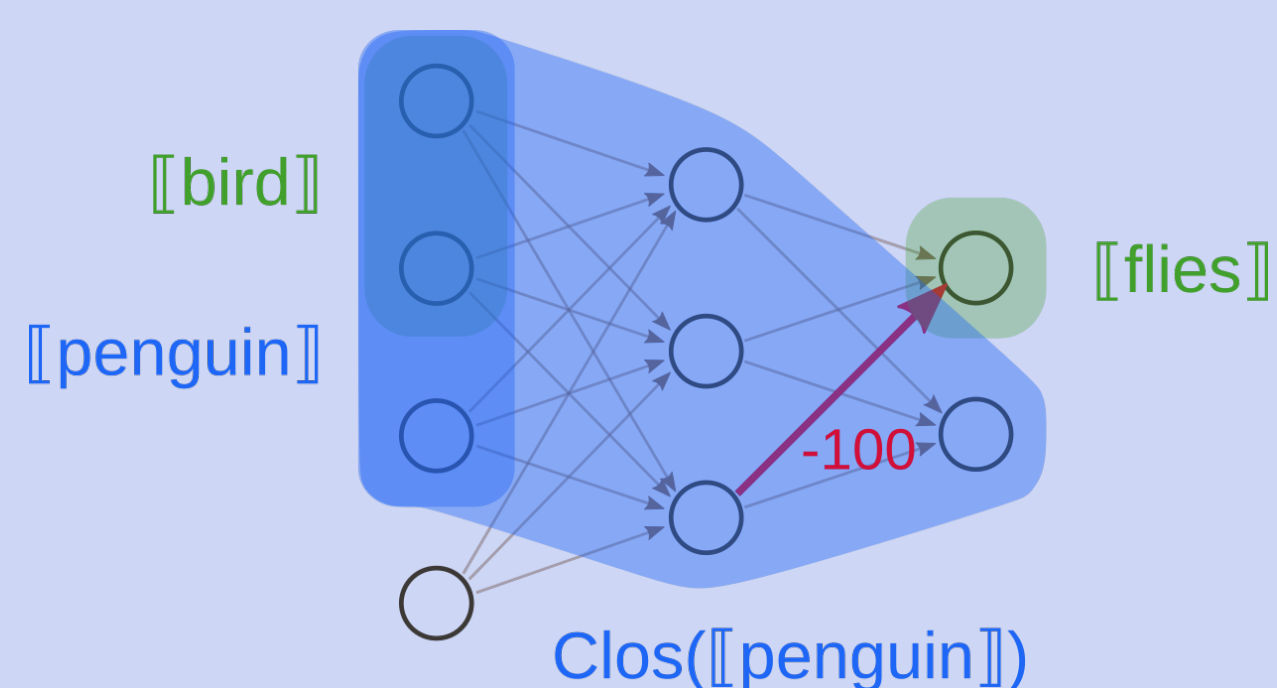
Note 2. C, K, E are the duals of $\langle C \rangle, \langle K \rangle, A$

Note 3. $A(\psi \rightarrow \langle C \rangle \varphi)$ is the same as $\varphi \Rightarrow \psi$

An Example

Here is an example net that satisfies some logic constraints:

- penguins $\rightarrow$ bird (*all penguins are birds*)
- $A(\text{flies} \rightarrow \langle C \rangle \text{bird})$ (*classify birds as flying*)
- $\neg A(\text{flies} \rightarrow \langle C \rangle \text{penguin})$ (*don’t classify peng. as flying*)



Soundness & Completeness

When a logic with neural network semantics is

- **Sound:** then we can formally verify that certain algebraic properties hold over this class of neural nets.
- **Complete:** then we can do **model-building**; for *any* finite set of constraints Γ over the logic, we can construct a neural network satisfying Γ .

Theorem. (Leitgeb 2003) $L_{\Rightarrow}$ has a sound and complete proof system $\vdash$ (the rules of **cumulative conditional logic**).

Theorem. L_C has a sound and complete proof system $\vdash$.

How do we do model-building? Design a **canonical neural net**, whose nodes are formulas α in “normal form.”

- Every finite Γ is equivalent to some normal form α
- Pick edges, weights, and activation function so that

$$\alpha \in \text{Clos}(\llbracket \varphi \rrbracket) \quad \text{iff} \quad \vdash \alpha \rightarrow \langle C \rangle \varphi$$

Expressivity

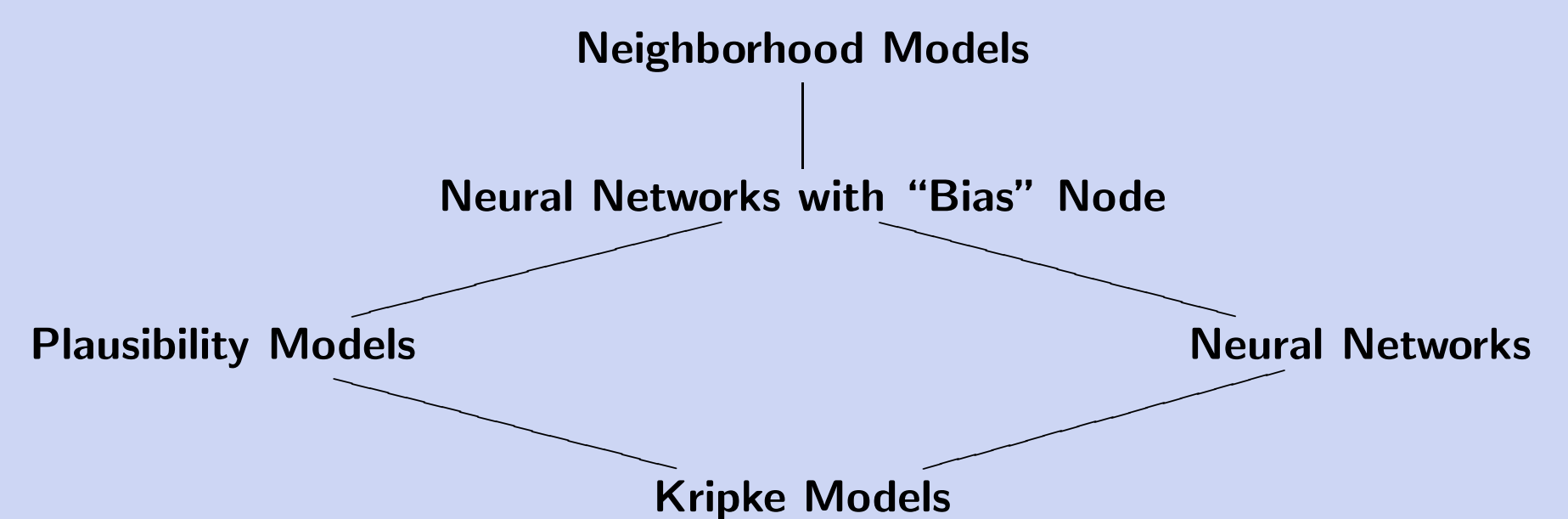
What classes of models can neural networks simulate?

Note: This is not quite the same as **descriptive complexity** (“What properties/functns. are definable over neural nets?”)

Definition. A class of models C_2 can **simulate** C_1 if there is injective $f: C_1 \rightarrow C_2$ such that $\forall M \in C_1$ and $\forall \varphi \in L$,

$$M \models \varphi \quad \text{iff} \quad f(M) \models \varphi$$

Theorem. Over L_C , we have the following lattice, where each class can simulate the models in the classes below it.

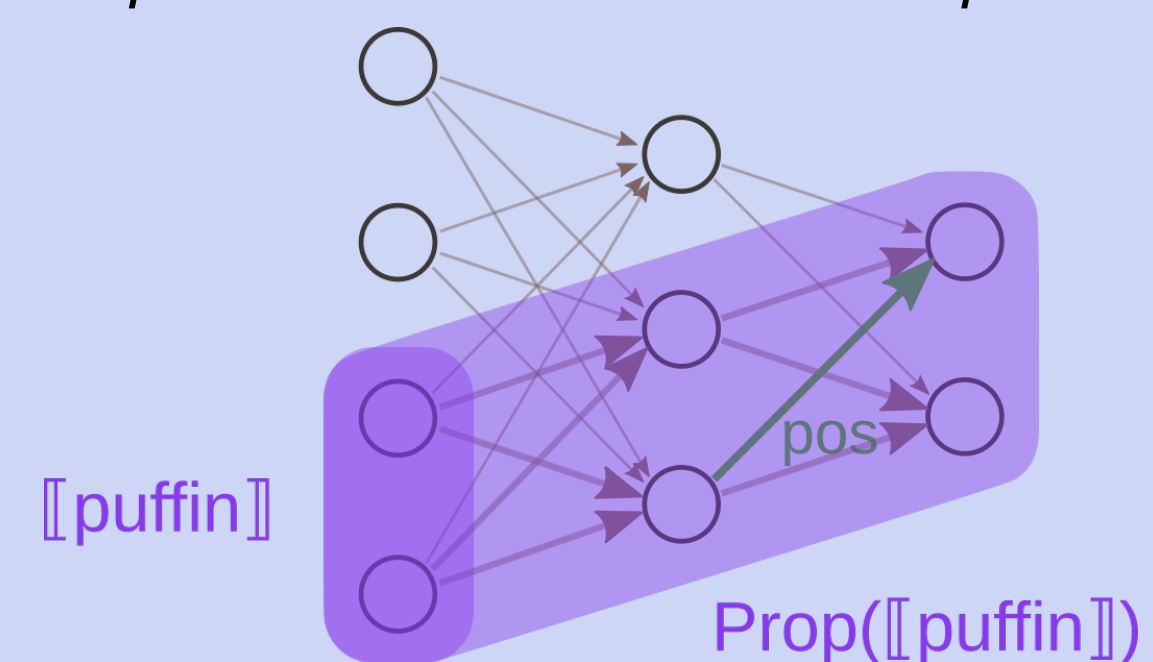


Neural Network Update

We can model neural network learning using **dynamic logic**! Add to L_C dynamic formulas $[\varphi]\psi$, which reads “ ψ holds after a simple neural network update on input φ .”

As a proof-of-concept, I’ve worked this out for a simple update. Consider **strong Hebbian learning**, which says

*Neurons that fire together wire together;
Repeat until we reach a fixed point.*



Let $\text{Hebb}(N, S)$ be the net obtained by increasing the weights of N within $\text{Clos}(S)$ until they are “maximally high.”

We interpret $[\varphi]\psi$ in the semantics by:

$$N, n \Vdash [\varphi]\psi \quad \text{iff} \quad \text{Hebb}(N, \llbracket \varphi \rrbracket), n \Vdash \psi$$

Assume: N is fully connected, activation is binary step

Theorem. L_{Hebb} can be completely axiomatized by “translating away” $[\varphi]\psi$ over L_C . The key reduction axiom is:

$$[\varphi]C\psi \leftrightarrow C([\varphi]\psi \wedge (C\varphi \vee K(C\varphi \vee C[A]\psi)))$$

Future Work

- What is the relationship between these expressivity results and the FLaNN community’s work on NN expressivity?
- Can we axiomatize gradient descent / backpropagation?
- Can we use neural network model building in practice to constrain nets throughout their training? (AI Alignment)

Dissertation Draft (in progress):

caleb.schultzkisby.me/Research_Papers/Dissertation/dissertation.pdf

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